

$$\text{Let } A = \begin{bmatrix} 0 & 2 & 2 & 4 & 2 & 4 \\ 1 & 6 & 3 & 9 & 2 & 3 \\ -2 & 3 & 4 & 12 & 3 & 8 \\ 3 & 6 & 0 & 3 & -1 & -5 \\ 1 & 2 & -1 & 1 & -1 & -3 \end{bmatrix}; \text{ then } \text{rref}(A) = \begin{bmatrix} 1 & 0 & 0 & -3 & 0 & -1 \\ 0 & 1 & 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Let $S = \{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_6\}$ be the set of column vectors of A .

1. Write all solutions of $A\mathbf{x} = \mathbf{0}$ in parametric vector form:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 3x_4 + x_6 \\ -2x_4 + 0x_6 \\ \mathbf{0} \\ x_4 \\ 0x_4 - 2x_6 \\ x_6 \end{bmatrix} = x_4 \begin{bmatrix} 3 \\ -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_6 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

where x_4 and x_6
are free.

always write the
at the end!

2. It's clear that S is LD. Which vectors in S can be expressed as linear combinations (LC's) of the other vectors? Don't write the vectors out; use their names ($\mathbf{a}_1, \mathbf{a}_2$, etc.) in a simple list instead.

According to (1), we'll be able to find ways to write $\vec{0}$ as $x_1\vec{a}_1 + x_2\vec{a}_2 + \dots + x_6\vec{a}_6 = \vec{0}$
where x_1, x_2, x_4, x_5, x_6 don't need to be 0; so of the corresponding
vectors $\vec{a}_1, \vec{a}_2, \vec{a}_4, \vec{a}_5$ at \vec{a}_6 can be written as LC's of the others
(but not \vec{a}_3 ... see 4 below!)

3. If \mathbf{a}_2 can be written as a LC of the other vectors, find a way to do it using as few of the other vectors as possible. Otherwise, explain correctly why \mathbf{a}_2 is not a LC of the other vectors.

the idea is to find a soln of $A\vec{x} = \vec{0}$ in which the weight in front of \vec{a}_2 is NOT 0.

try $x_4 = 1$ and $x_6 = 0$. then the other weights are $x_1 = 3 \cdot 1 + 0$
 $x_2 = -2 \cdot 1 + 0$
($x_3 = 0$ always)
 $x_5 = -2 \cdot 0$

$$\text{so } 3\vec{a}_1 + 2\vec{a}_2 + 0\vec{a}_3 + 1\vec{a}_4 + 0\vec{a}_5 + 0\vec{a}_6 = \vec{0}$$

or, $3\vec{a}_1 - 2\vec{a}_2 + \vec{a}_4 = \vec{0}$. solve for \vec{a}_2 to find

$$\vec{a}_2 = \frac{1}{2}(3\vec{a}_1 + \vec{a}_4); \text{ finally then } \boxed{\vec{a}_2 = \left(\frac{3}{2}\right)\vec{a}_1 + \left(\frac{1}{2}\right)\vec{a}_4}$$

shows how to write \vec{a}_2 as a LC of \vec{a}_1 & \vec{a}_4 .

4. If \mathbf{a}_3 can be written as a LC of the other vectors, find a way to do it using as few of the other vectors as possible. Otherwise, explain correctly why \mathbf{a}_3 is not a LC of the other vectors.

The vector \vec{a}_3 cannot be written as a LC of the other vectors.

For suppose it CAN BE. then $\vec{a}_3 =$ (some LC of the other vectors)

$$\text{so } \vec{a}_3 = x_1\vec{a}_1 + x_2\vec{a}_2 + x_4\vec{a}_4 + x_5\vec{a}_5 + x_6\vec{a}_6 \text{ for some weights } x_1, x_2, \dots, x_6$$

$$\text{subtract } \vec{a}_3 \text{ from both sides: } \vec{0} = x_1\vec{a}_1 + x_2\vec{a}_2 + (-1)\vec{a}_3 + x_4\vec{a}_4 + x_5\vec{a}_5 + x_6\vec{a}_6$$

BUT our solution of $A\vec{x} = \vec{0}$ in (1) tells us that in ANY soln of $A\vec{x} = \vec{0}$, the
weights x_3 of \vec{a}_3 is 0, yet here's a soln with $x_3 = -1$, a contradiction,
since x_3 can't be both 0 and -1. So \vec{a}_3 is NOT a LC of the others.